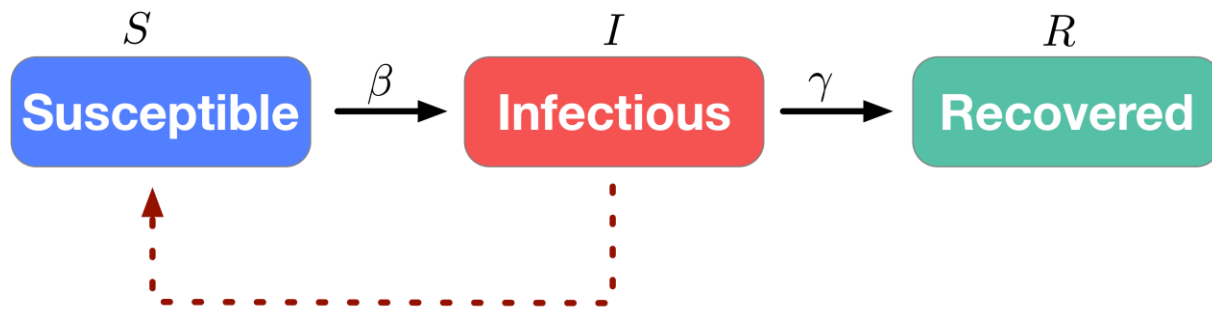


# Introduction to MCMC for Infectious Diseases

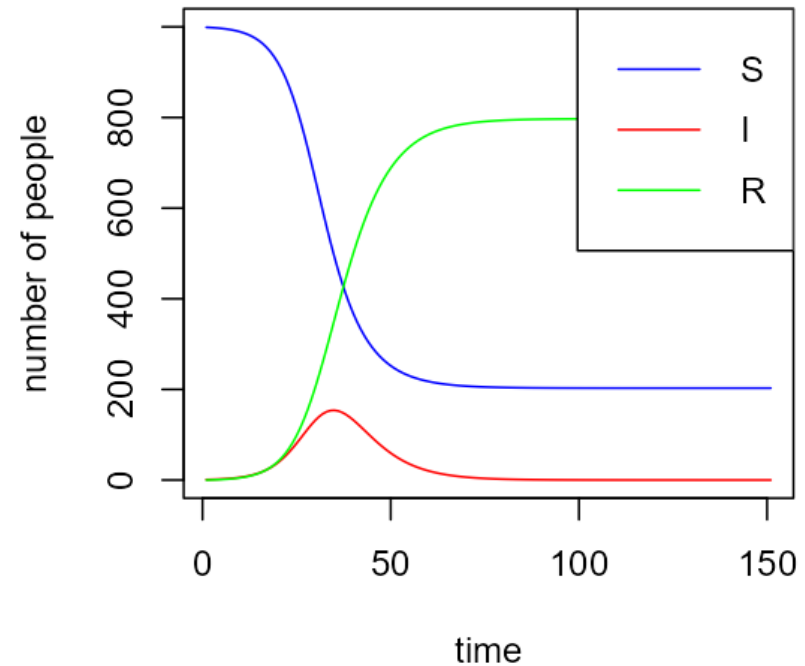
CCB Skills Seminar – 10/10/2024

Philip Lee

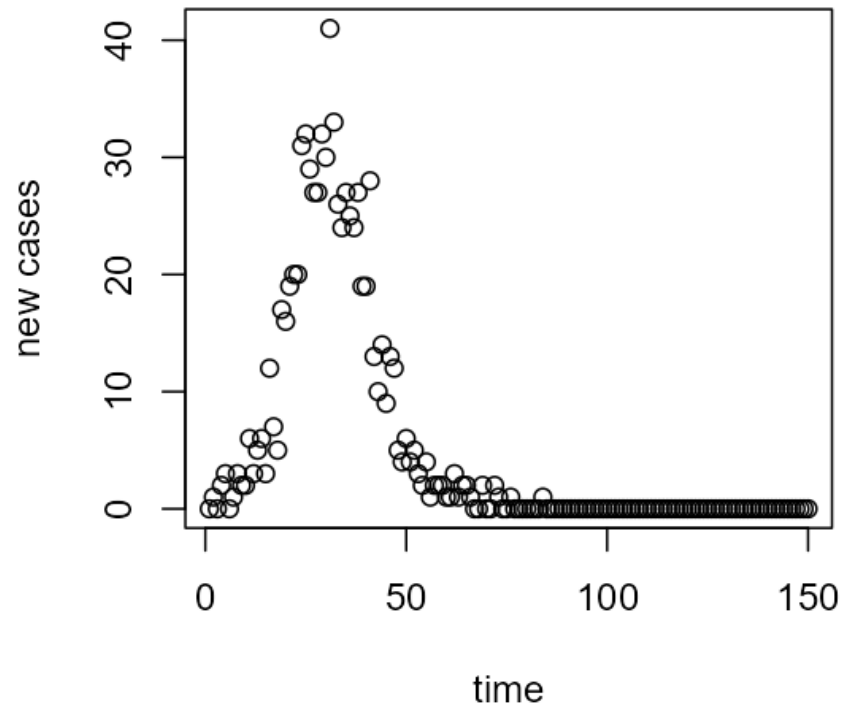
# Long history of modeling infectious disease transmission



$$\begin{aligned}\frac{dS}{dt} &= -\beta SI/N \\ \frac{dI}{dt} &= \beta SI/N - \gamma I \\ \frac{dR}{dt} &= \gamma I\end{aligned}$$

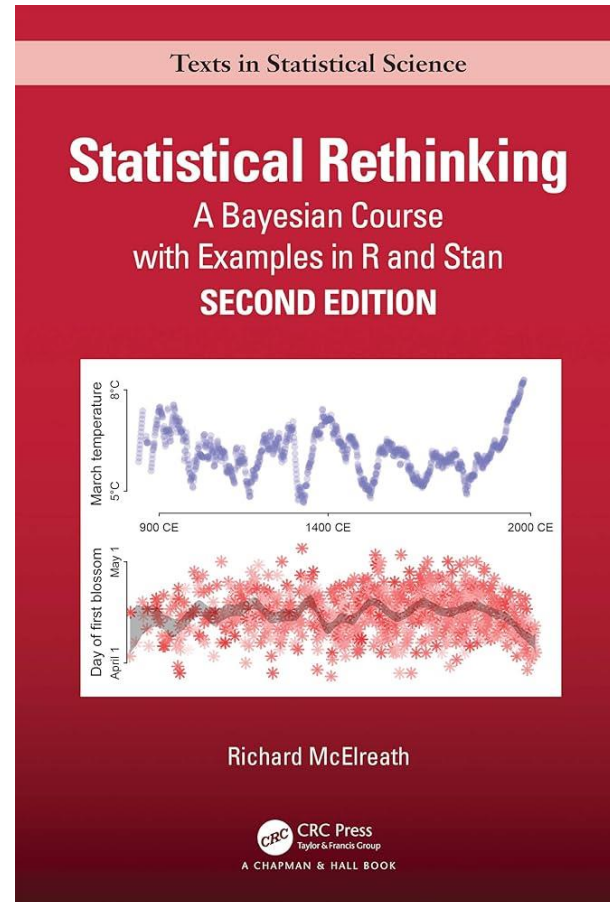


Given data, what can we say about our model parameters?



$$\begin{aligned}\frac{dS}{dt} &= -\beta SI/N \\ \frac{dI}{dt} &= \beta SI/N - \gamma I \\ \frac{dR}{dt} &= \gamma I\end{aligned}$$

# Resource for Bayesian statistics



# Bayesian inference

- **Observed data**: e.g., number of observed infections ( $D$ )
- **Probability model**: how is the observed data generated?
  - Model is parameterized by  $\theta \in \Theta$
- **Fitting the model**: we want to find  $\theta$  that have high probability given our observed data
  - We want  $P(\theta|D)$  to be large
  - i.e., we want to find “highly plausible”  $\theta$  given our data

# Bayesian updating

- **Bayes' rule** tells us how to compute these “plausibilities”:

$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{P(D)}$$

- $P(\theta)$  is the **prior probability**
- $P(D|\theta)$  is the **likelihood**
- $P(D)$  is a normalizing constant
- $P(\theta|D)$  is the **posterior probability**

# Globe tossing example

- Toss globe 9 times: observe  $W = 6$  water and  $L = 3$  land
- What's the proportion  $p$  of Earth that is covered in water?



- Observed data  $D = (W, L)$
- Binomial model with parameter  $p$ 
  - $W \sim \text{Binom}(p)$
- **Question:** which  $p$  are most plausible given our data?

# Globe tossing Bayesian updating

- Apply Bayes' rule:

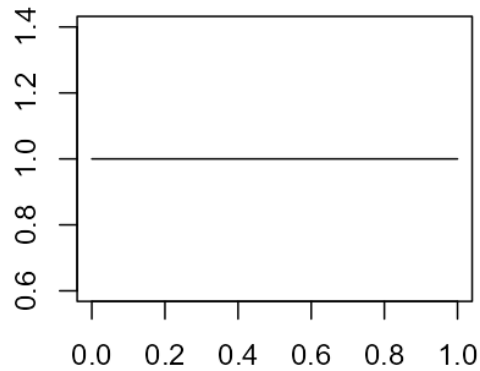
$$P(p|W) = \frac{P(W|p)P(p)}{P(W)} \quad P(p|W) \propto P(W|p)P(p)$$

- **Binomial likelihood:**  $P(W|p) = \binom{W+L}{W} p^W (1-p)^L$
- **Uniform prior:**  $P(p) = 1$



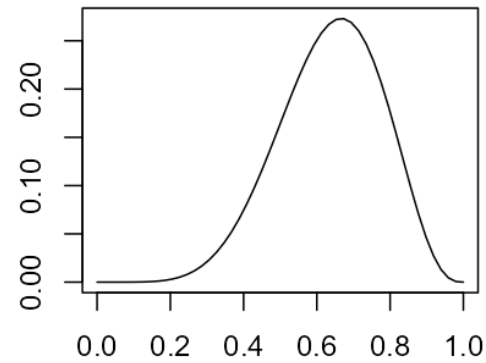
# Globe tossing Bayesian updating

**Prior**



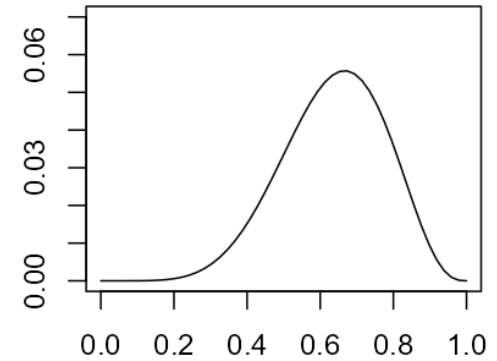
$\times$

**Likelihood**



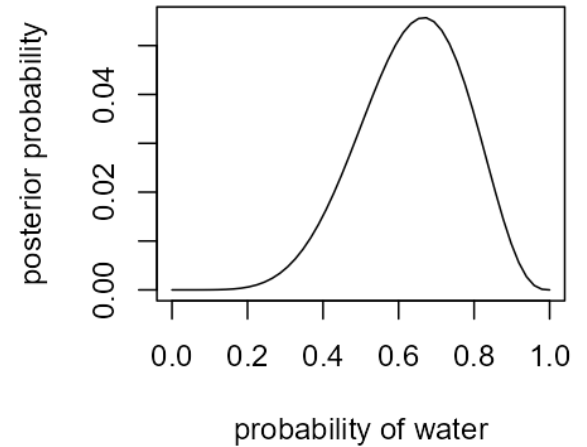
$\propto$

**Posterior**



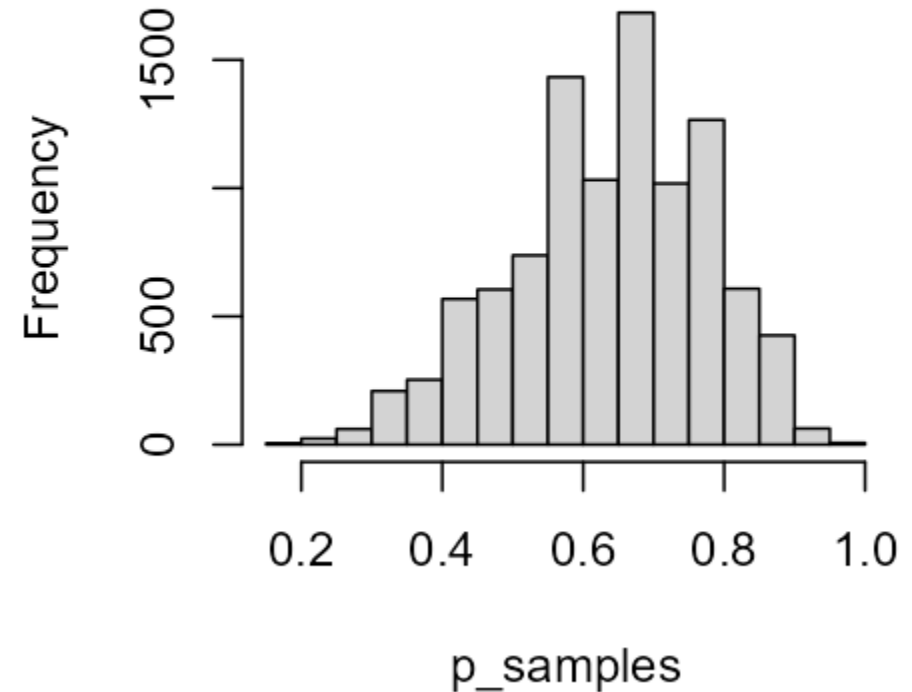
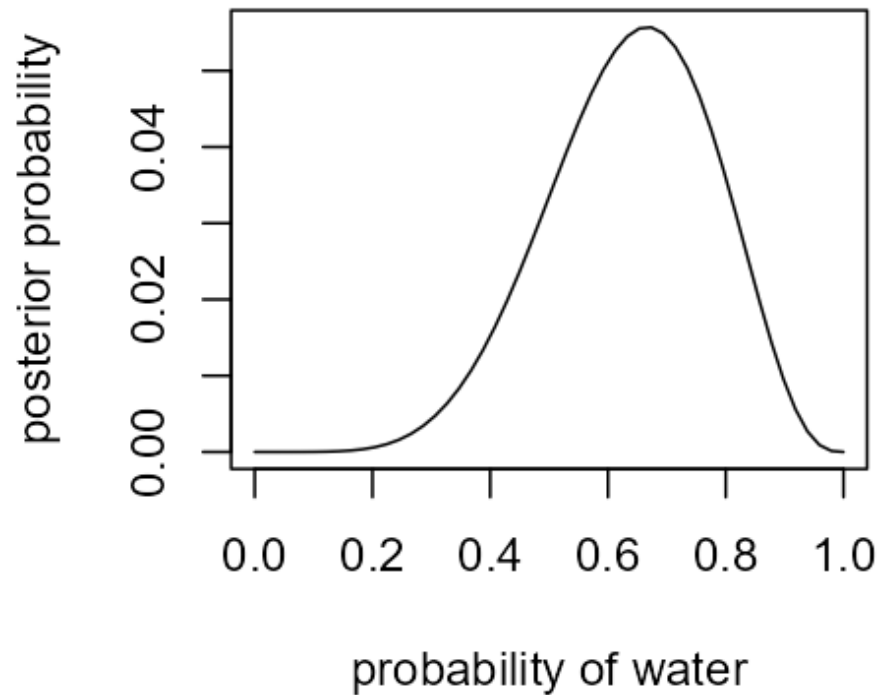
# Analyzing the Bayesian estimate

- The **entire** posterior distribution is the Bayesian estimate!
- Extract **point estimates**
  - Find the parameter value with highest probability (MAP estimate)
  - Find the median parameter value (50% quantile)
- Extract **credible intervals**
  - e.g., find the 2.5% and 97.5% quantiles of the parameter values
- Make **posterior predictions**
  - Simulate new data taking into account all of the uncertainty embodied in the posterior distribution

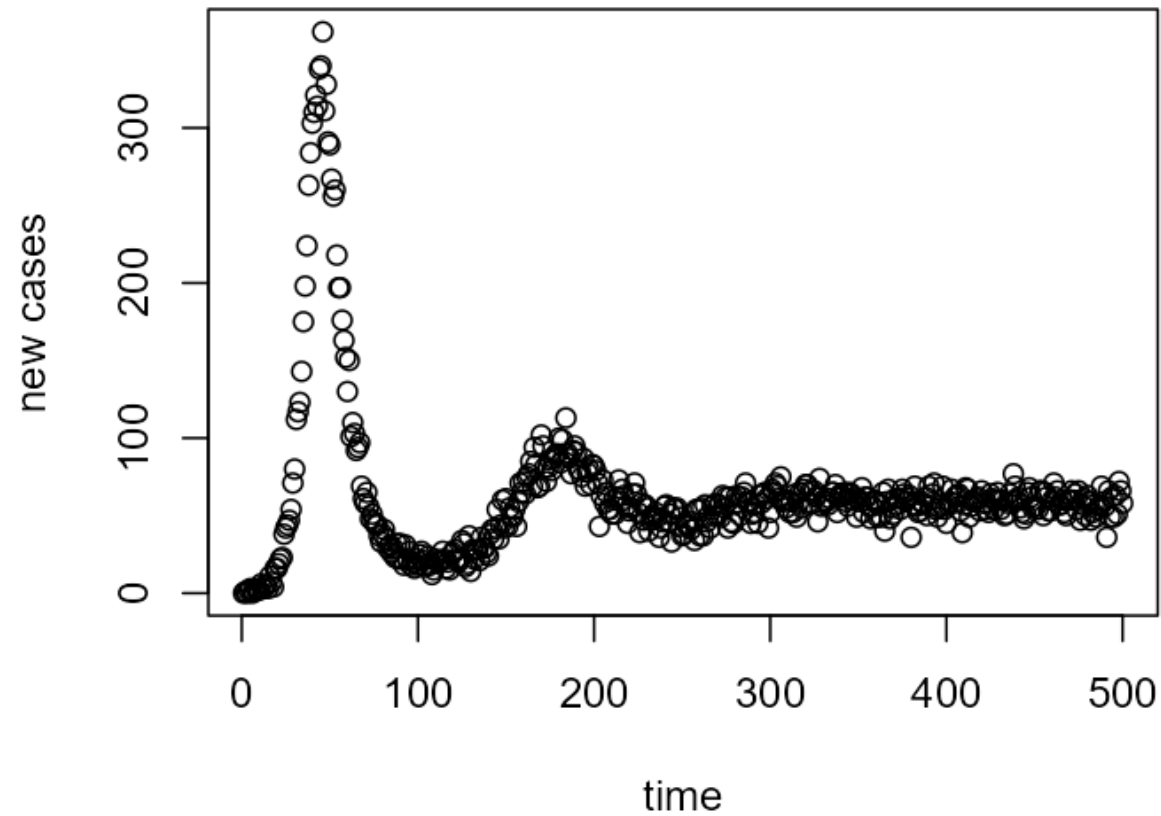


# Sampling from the Bayesian estimate

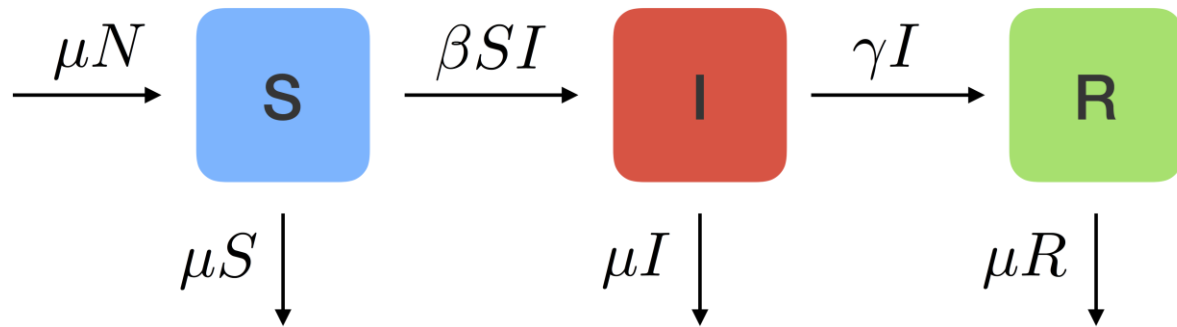
- Usually easier to work with samples from the posterior



# What can we learn from this data?



# Need to add demographic processes to obtain periodic case trajectories



$$\begin{aligned}\frac{dS}{dt} &= \mu N - \beta SI/N - \mu S \\ \frac{dI}{dt} &= \beta SI/N - \gamma I - \mu I \\ \frac{dR}{dt} &= \gamma I - \mu R\end{aligned}$$

# Key epidemiological parameter: $R_0$

- Average number of secondary cases that an infectious individual would generate in a completely susceptible population
  - $R_0 < 1$ : no outbreak
  - $R_0 > 1$ : yes outbreak

$$\frac{dS}{dt} = \mu N - \beta SI/N - \mu S$$

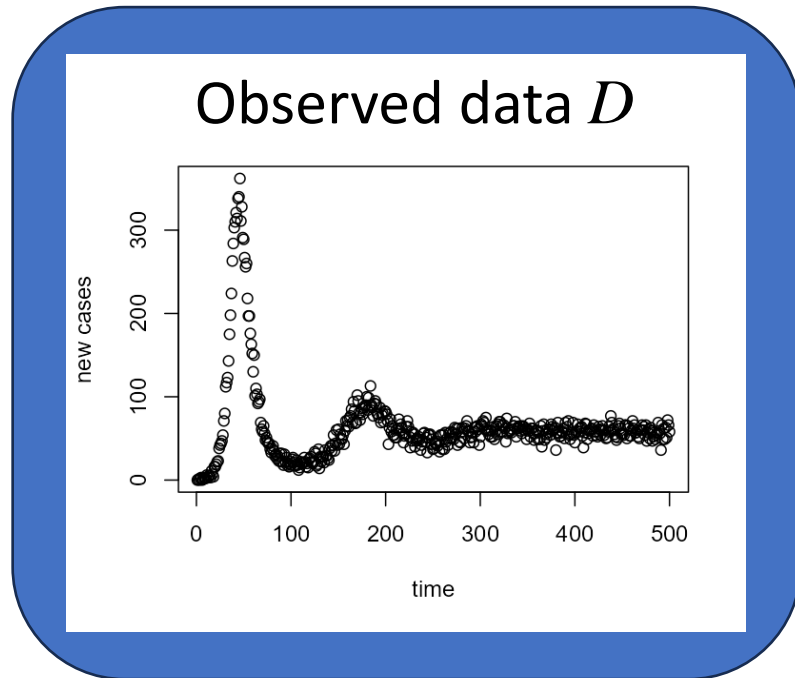
$$\frac{dI}{dt} = \beta SI/N - \gamma I - \mu I$$

$$\frac{dR}{dt} = \gamma I - \mu R$$



$$R_0 = \frac{\beta}{\gamma + \mu}$$

# Perform inference on $R_0$



Probability model  
(assume cases Poisson distributed)

$$\begin{aligned}\frac{dS}{dt} &= \mu N - \beta SI/N - \mu S \\ \frac{dI}{dt} &= \beta SI/N - \gamma I - \mu I \\ \frac{dR}{dt} &= \gamma I - \mu R\end{aligned}$$

Likelihood:  $P(D|R_0)$

Prior:  $P(R_0)$

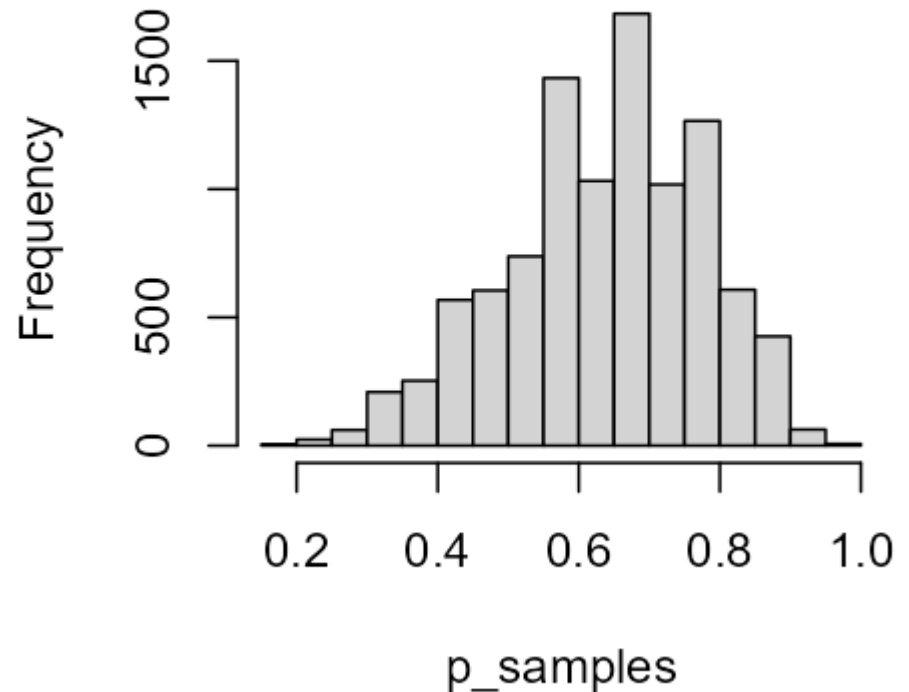
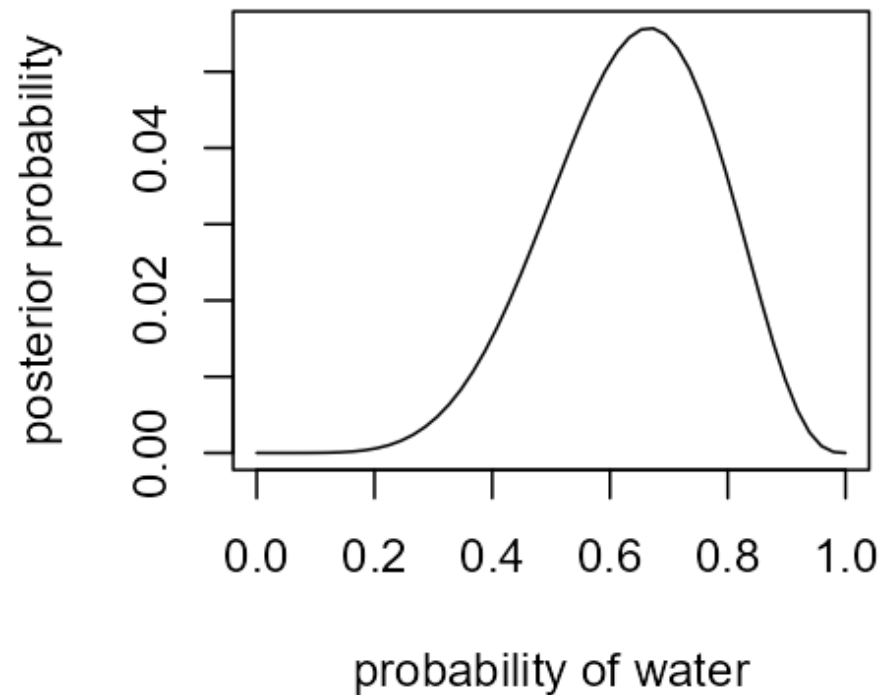
# Grid approximation can fail

- Globe tossing example: choose a discrete set of  $p$  values and compute the posterior probability for each  $p$  value
- Can we do something similar with  $R_0$  values instead?
  - Problem:  $P(D|R_0)$  values are extremely small
  - Could be numerical issues with trying to sample  $R_0$  values from a grid approximated posterior
- Grid approximation computationally infeasible with high-dimensional parameter spaces

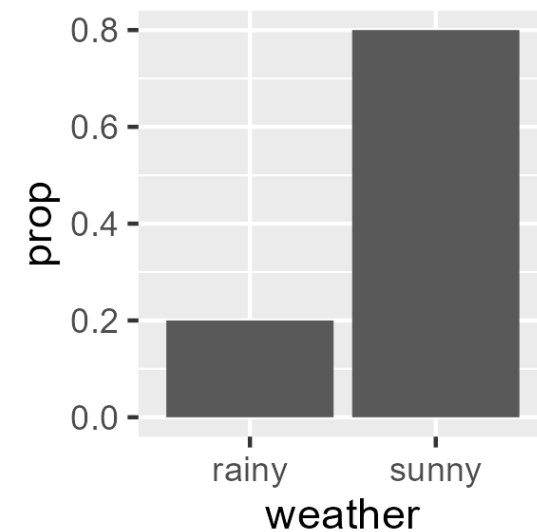
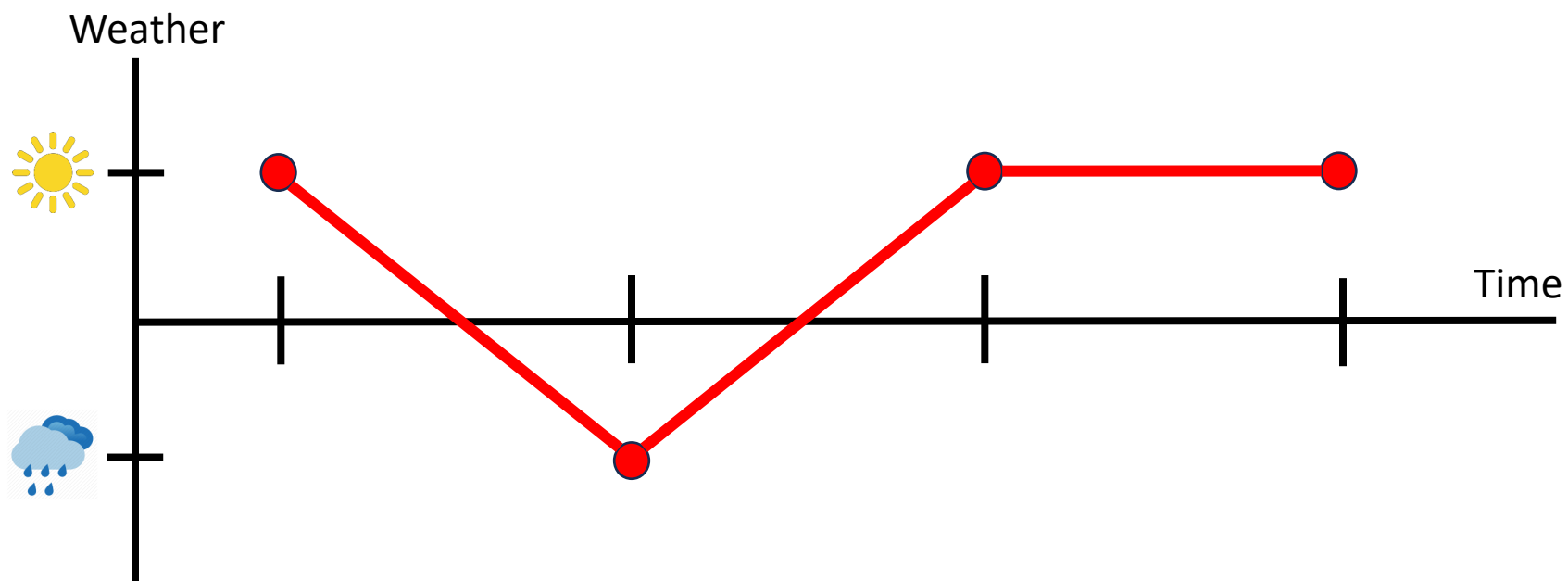
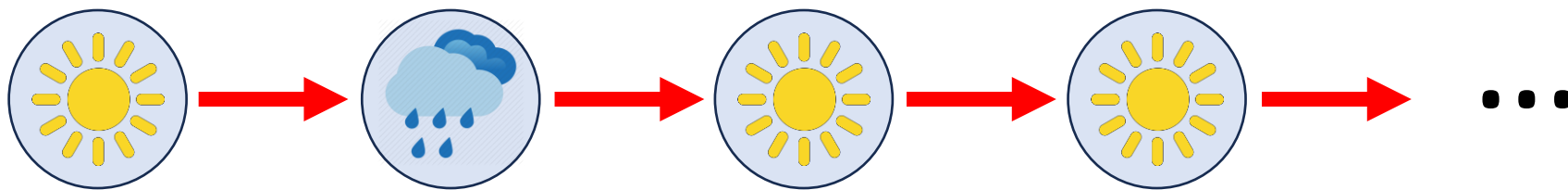


# Markov Chain Monte Carlo (MCMC)

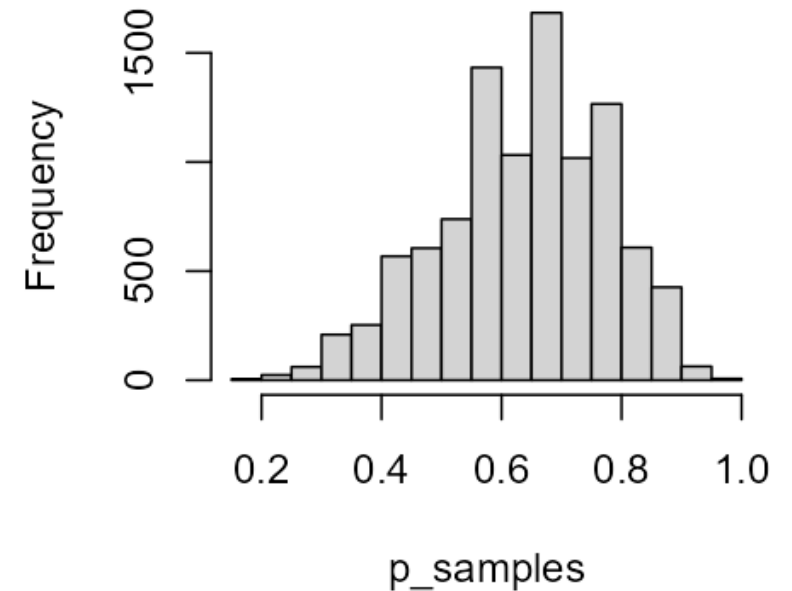
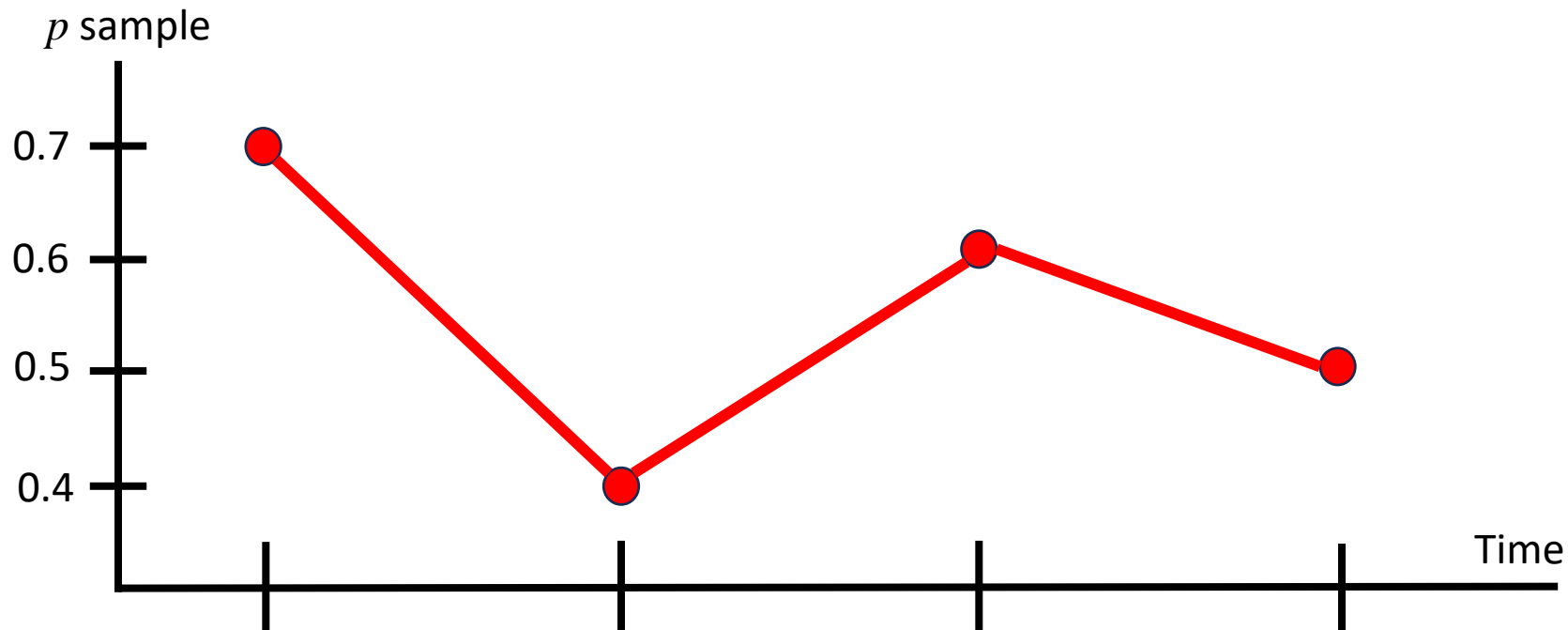
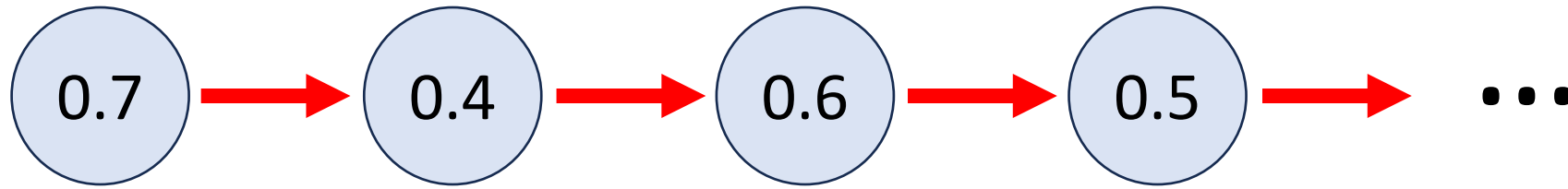
- Algorithm for obtaining **samples** from the posterior distribution without ever computing the actual posterior distribution



# Markov chains (weather space)

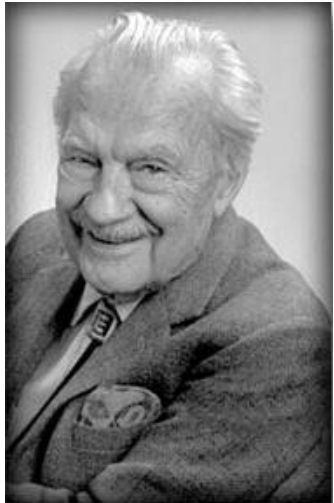


# Markov chains (proportion of water $p$ space)



# Metropolis-Hastings Algorithm

- Constructs a Markov chain that gives us parameter samples in proportion to their posterior probability



Nicholas  
Metropolis



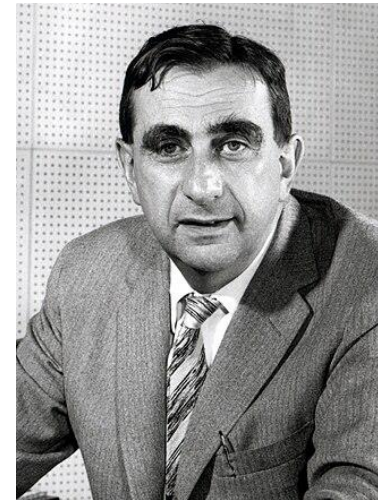
Arianna  
Rosenbluth



Marshall  
Rosenbluth



Augusta  
Teller



Edward  
Teller

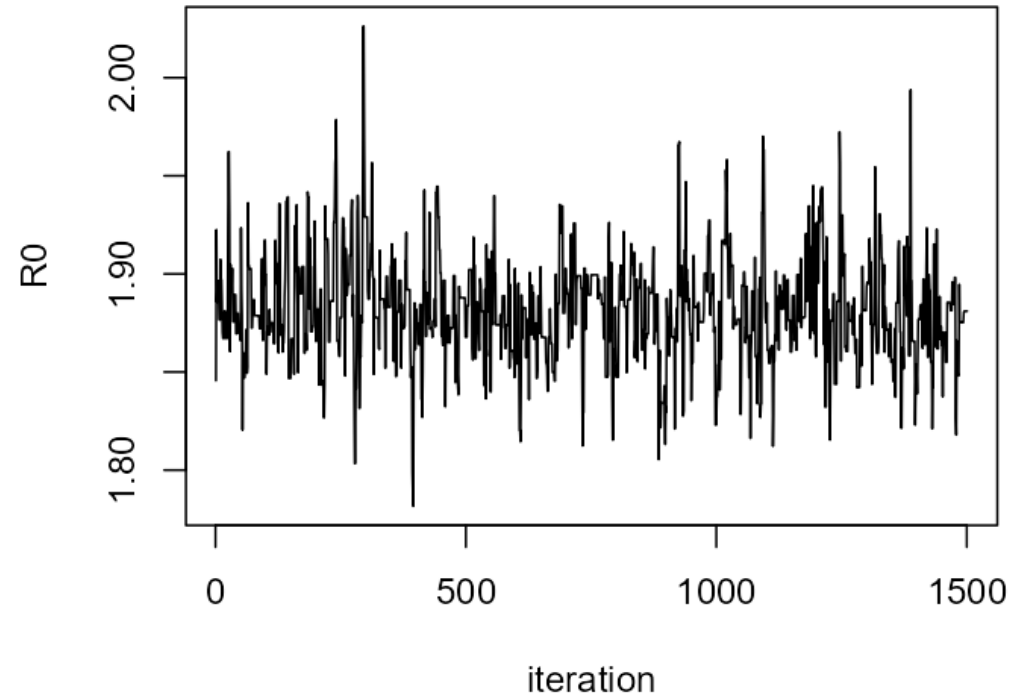
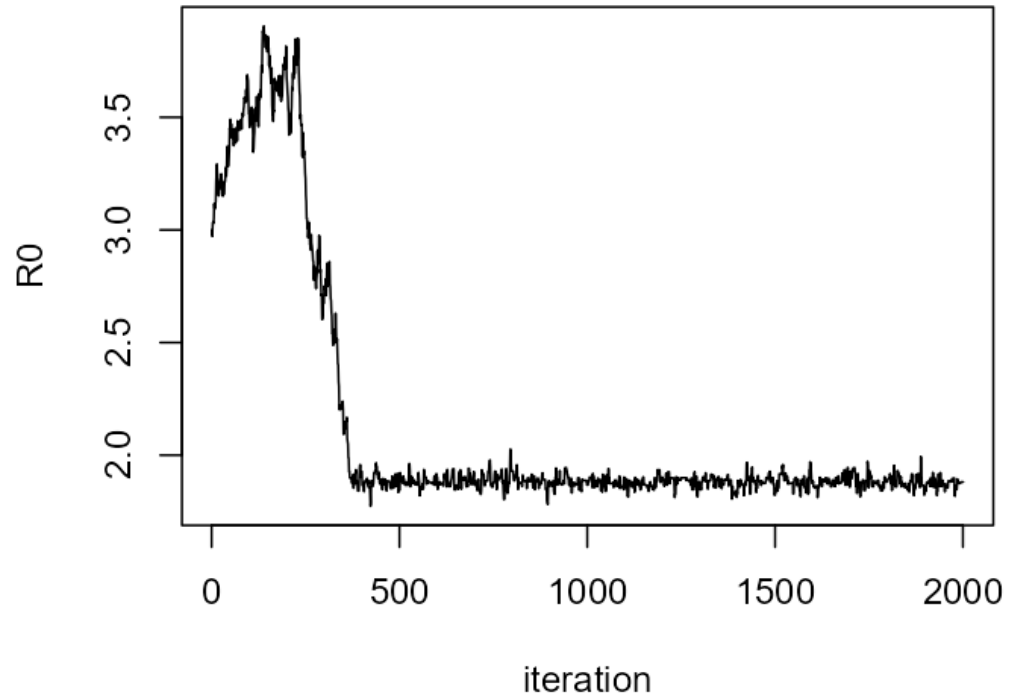


Wilfred  
Hastings

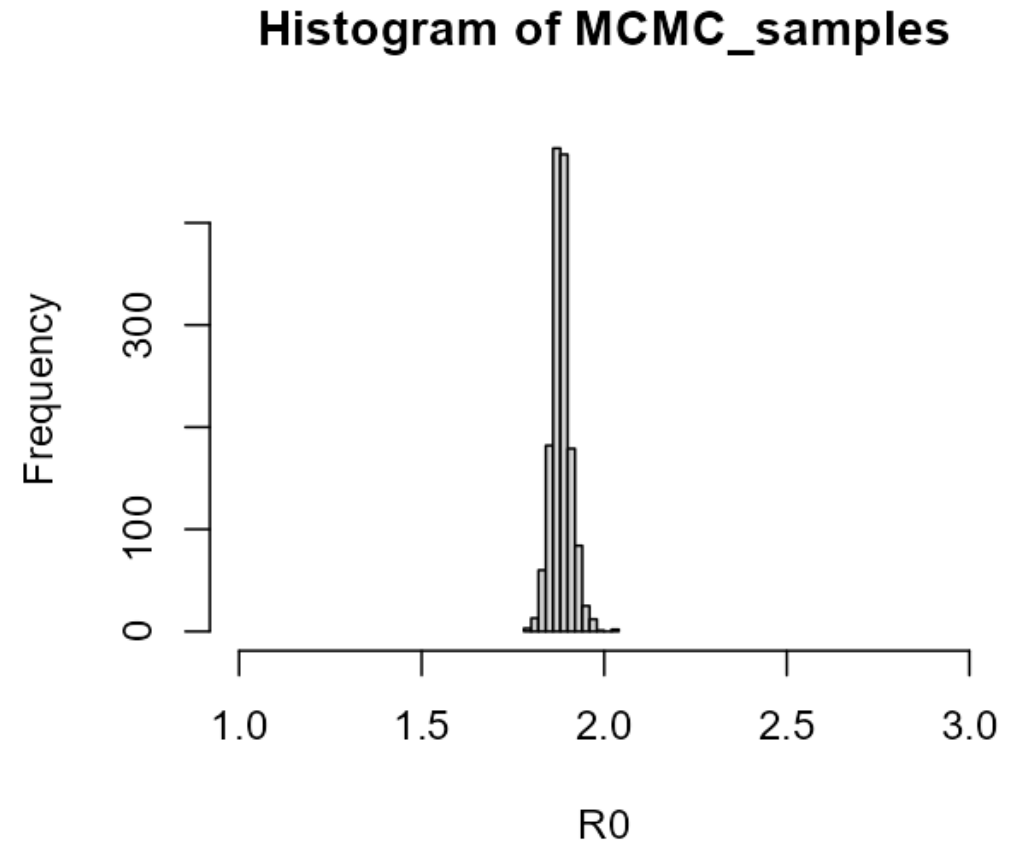
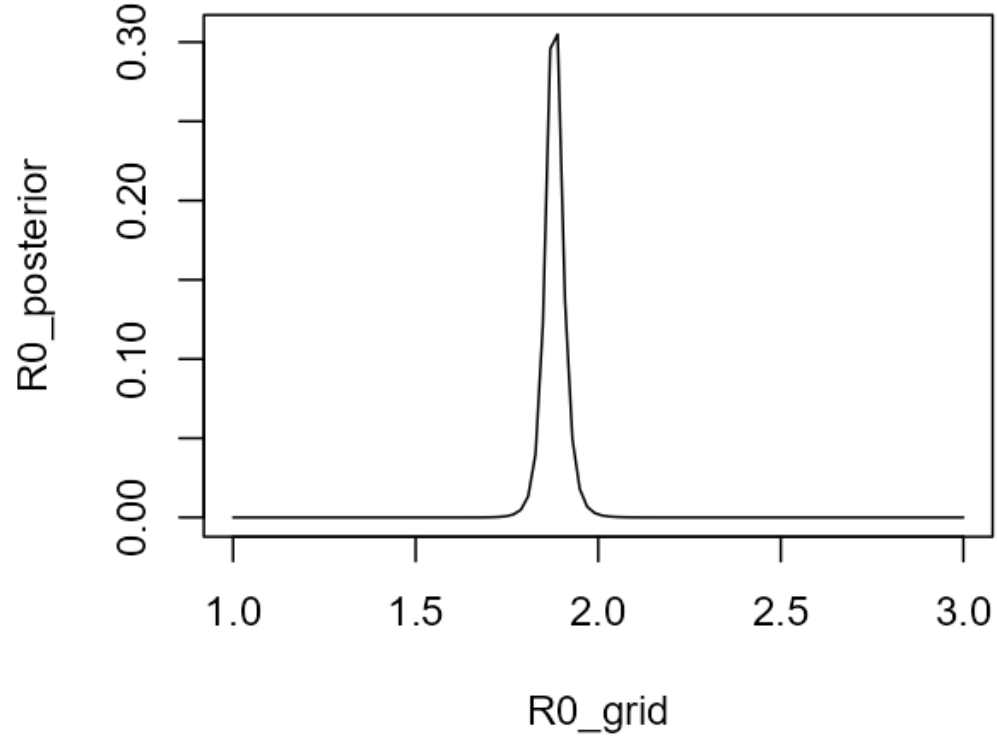
# Metropolis Algorithm

1. Start the chain at a parameter value  $\theta_0$
2. Choose a new parameter value ( $\theta^*$ ), based on the current parameter value ( $\theta$ )
3. If the  $P(D|\theta^*)P(\theta^*) > P(D|\theta)P(\theta)$ , move the chain to  $\theta^*$ . Otherwise, move the chain to  $\theta^*$  with probability  $P(D|\theta^*)P(\theta^*)/P(D|\theta)P(\theta)$
4. Repeat steps 2-3 until the distribution of parameter values converges

# Burn-in samples need to be removed

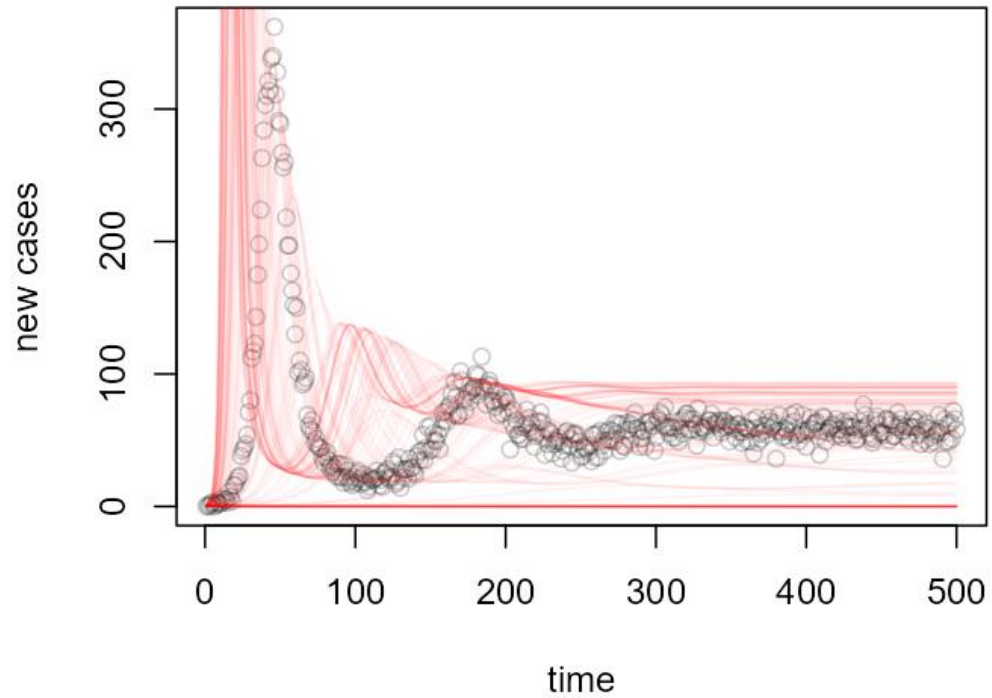


# Grid approximation versus MCMC

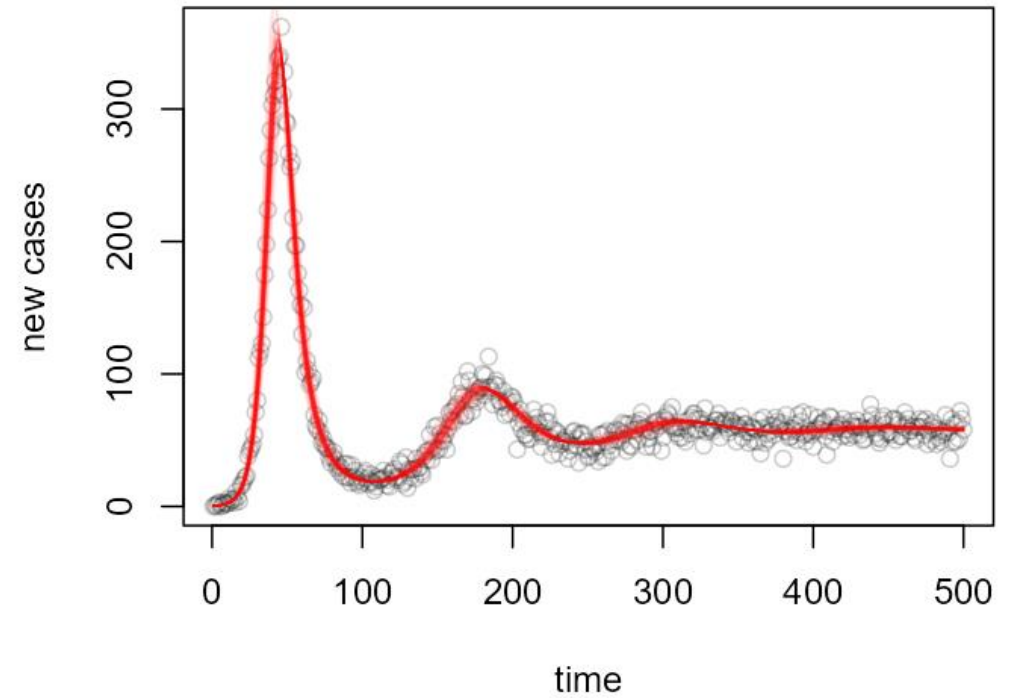


# Prior and posterior mean trajectories

Prior



Posterior





Thanks for listening!